

**LINE OPERATED A.C. MOTORS FOR SUBMERSIBLE PUMPSETS-SPECIFICATION (THIRD REVISION)**

Rotating Machinery Sectional Committee, ETD 15

**FOREWORD**

This draft Indian Standard (Third Revision) would be adopted by the Bureau of Indian Standards, after the draft finalized by the Rotating Machinery Sectional Committee had been approved by the Electrotechnical Division Council.

This standard shall be read in conjunction with IS 8034 : 2018 'Submersible pumpsets - Specification (Third Revision)' and IS 14220 : 2018 'Open well submersible pumpsets - Specification (First Revision)' as the submersible motor and the submersible pump together form a complete set. Coordination in the selection of motor and pump with respect to their size, rating and output, etc, is necessary for satisfactory and efficient operation of the pumpset.

The general requirements of 3-phase induction motors are covered in IS 12615: 2018 'Line operated three phase AC motors (IE Code) "Efficiency classes and performance specification" (Third Revision)' and requirements of single phase a.c. motors are specified in IS 996: 2009 'Single-phase ac induction motors for general purpose (third revision)'. The requirements of 3-phase squirrel cage induction motors for centrifugal pumps are covered in IS 7538: 1996 'Three-phase squirrel cage induction motors for centrifugal pumps for agricultural applications (first revision)'. The detailed procedure for conducting tests on motors are given in IS 4029: 2010 'Guide for testing three-phase induction motors (first revision)' and IS 7572: 1974 'Guide for testing single-phase ac and universal motors' as relevant. In this revision the following have been added:

- a) Values of Performance Characteristics for 2-Pole Three-Phase Submersible Motor — Oil Filled (Suitable for Bore Size 150 mm and Maximum outside Diameter of Motor 146 mm)
- b) Three efficiency levels for 2-Pole Three-Phase Submersible Motors (all performance characteristics tables).

Also, reference should be made to IS 10804 (Part 2): 2018 'Recommended pumping system for agricultural purposes: Part 2 submersible pump sets (Third Revision)'.

For the purpose of deciding whether a particular requirement of this standard is complied with, the final value, observed or calculated, expressing the result of a test or analysis, shall be rounded off in accordance with 'IS 2 : 2022 Rules for rounding off numerical values ( *revised* )'. The number of significant places retained in the rounded off value should be the same as that of the specified value in this standard.

## 1 SCOPE

This standard specifies technical requirements of submersible motors for submersible pumpsets commonly used in bore-holes (bore-wells or tube wells) and submersible pumpsets commonly used in open wells for handling clear, cold and fresh water for application in agriculture, water supply, etc.

## 2 REFERENCES

The standards listed at Annex A contain provisions, which through reference in this text, constitute provisions of this standard. At the time of publication, the editions indicated were valid. All standards are subject to revision, and parties to agreements based on this standard are encouraged to investigate the possibility of applying the most recent editions of the standards.

## 3 TERMINOLOGY

For the purpose of this standard, the definitions given in IS 1885 (Part 35) and the following shall apply.

**3.1 Wet Type Water Filled Submersible Motors** — It is a motor, which is completely filled with clear water (*see* Fig. 1).

**3.2 Wet Type Oil Filled Submersible Motors** — It is a motor, where winding as well as entire remaining space within the motor is filled with non-toxic grade of oil and effectively sealed (*see* Fig. 2).

**3.3 Resin Filled Submersible Motors** — It is a motor, where the stator is encapsulated and filled with an insulating compound. The remaining portion is filled with water or oil (*see* Fig. 3).

## 4 CHARACTERISTICS OF CLEAR, COLD AND FRESH WATER

Clear, cold, and fresh water means water having the characteristics specified below:

- |   |   |                                   |
|---|---|-----------------------------------|
| a) Turbidity  | : | 50 ppm (silica scale), <i>Max</i> |
| b) Chlorides  | : | 500 ppm, <i>Max</i>               |
| c) Total solids   | : | 3000 ppm, <i>Max</i>              |
| d) pH value   | : | 6.5 to 8.5                        |
| e) Temperature  | : | 33°C, <i>Max</i>                  |
| f) Specific gravity                                     | : | 1.004, <i>Max</i>                 |
| g) Hardness (as CaCO <sub>3</sub> )<br>(drinking water) | : | 300 mg/litre, <i>Max</i>          |

NOTE — If any other characteristics of water differ from these specified in 4.1, the pump details shall be as agreed to between the manufacturer/supplier and the user and shall be specified in the order.

## 5 CONSTRUCTION

The nomenclature of various components in the assembly of submersible pumpset is given in Fig. 1 to Fig. 3. The typical submersible pumpset installation is given in Fig. 4 for information.

5.1 The nomenclature of various components in the assembly of submersible pumpset is given

in Figs. 1, 2 and 3. The typical submersible pumpset installation is given in Fig. 4 for information.

5.1.1 All the materials and components for the motors shall be suitable for application in respect of corrosion resistance and mechanical performance continuously under

water. The typical materials used in the submersible motors are given in Table 1 for the guidance of the manufacturer and the user.

5.1.2 The rotor of the wet type submersible motor shall be provided with suitable epoxy paint to protect it from corrosion under water.

5.1.3 The thrust bearing housing shall be provided with a drain plug to empty the oil/water filled into the thrust bearing housing/motor.

5.1.4 The motor shall be provided with a breathing attachment like bellows, diaphragm, etc. to compensate for the volumetric variation of water inside the motor due to changes in the temperature.

## **5.1 Earthing**

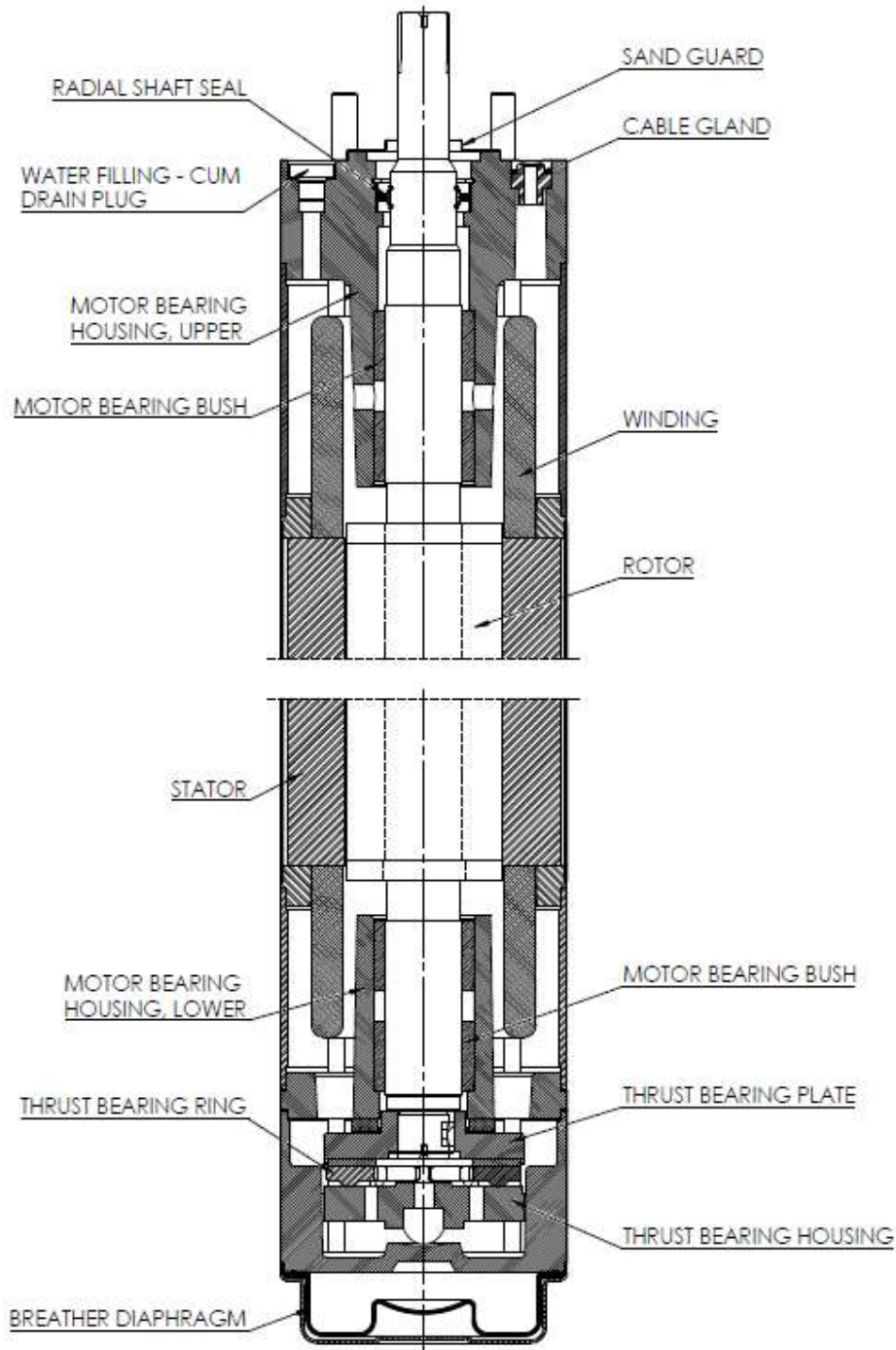
Motor shall have suitable provision for earthing to facilitate earthing of the motor as per clause 11.1 of IS 15999 (Part 1) at the time of installation.

In case GI pipes are used for the purpose of earthing the motor, earthing connection may be made to the discharge pipe clamps.

All the materials and components for the motors shall be suitable for application in respect of corrosion resistance and mechanical performance continuously under water. The typical materials used in the submersible motors are given in Table 1 for the guidance of the manufacturer and the user.

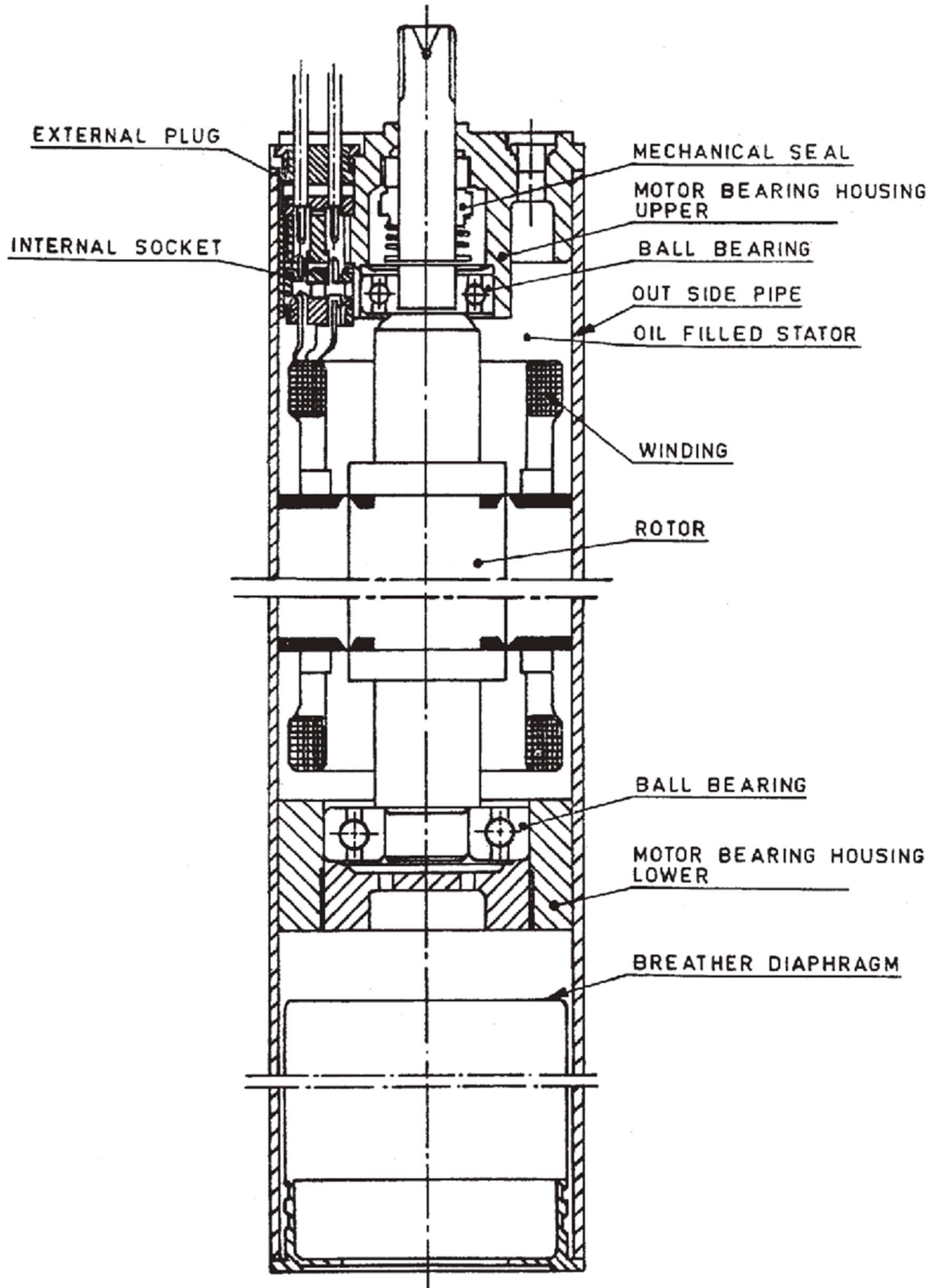
The rotor of the wet type submersible motor shall be provided with suitable coating to protect it from corrosion under water.

The motor shall be provided with a breathing attachment like bellows, diaphragm, etc. to compensate for the volumetric variation of water inside the motor due to changes in the temperature.



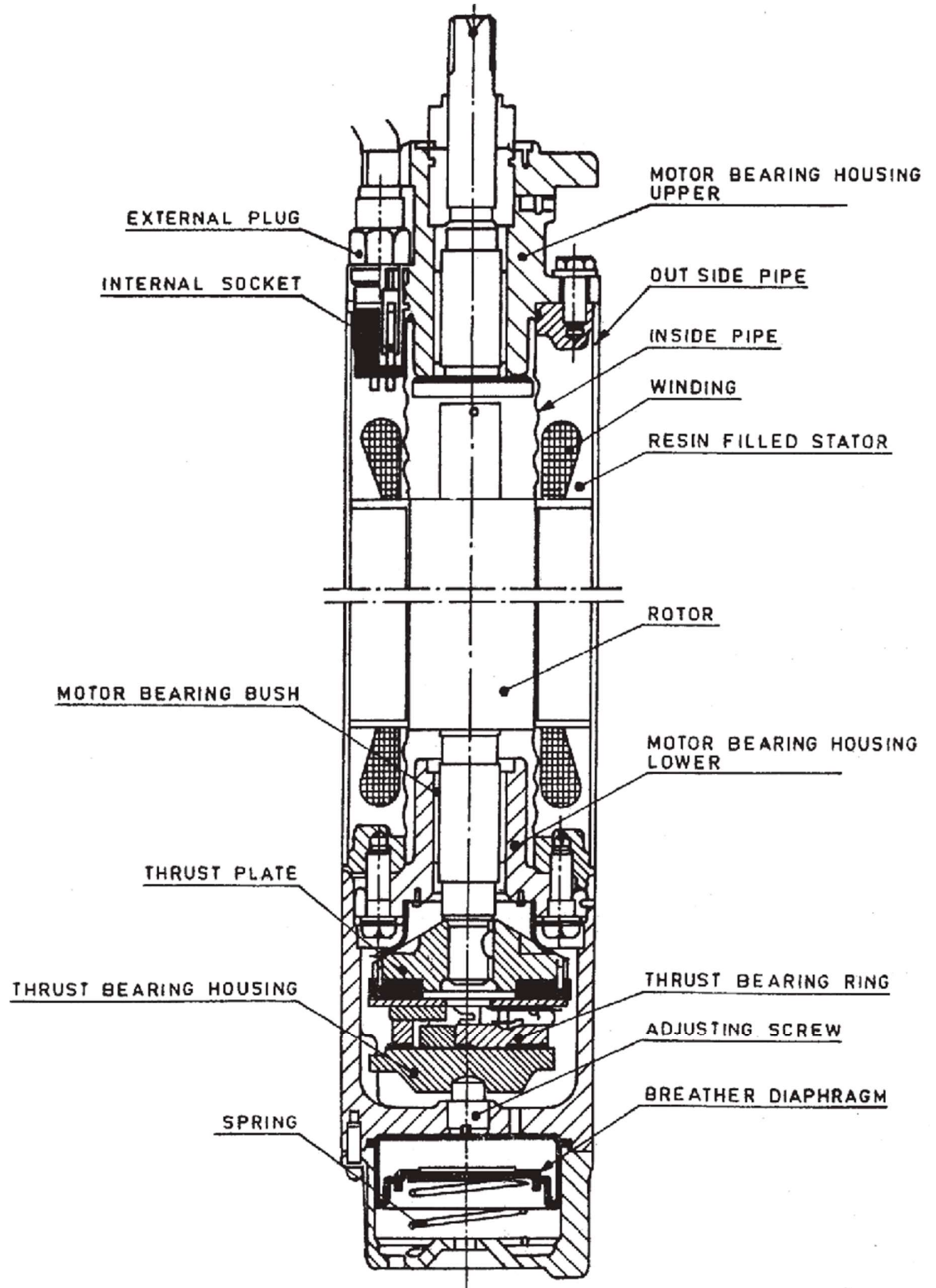
NOTE — This figure only illustrates the nomenclature of commonly used parts and does not specify any particular design feature.

**FIG 1 WET TYPE WATER FILLED SUBMERSIBLE MOTOR**



NOTE — This figure only illustrates the nomenclature of commonly used parts and does not specify any particular design feature.

**FIG 2 WET TYPE OIL FILLED SUBMERSIBLE MOTOR**



NOTE — This figure only illustrates the nomenclature of commonly used parts and does not specify any particular design feature.

**FIG 3 RESIN FILLED SUBMERSIBLE MOTOR**



## 5.2 Foreign Matter

The motor shall be protected by means of cable glands, rubber seals, etc., from ingress of borewell water, sand and other foreign matter.

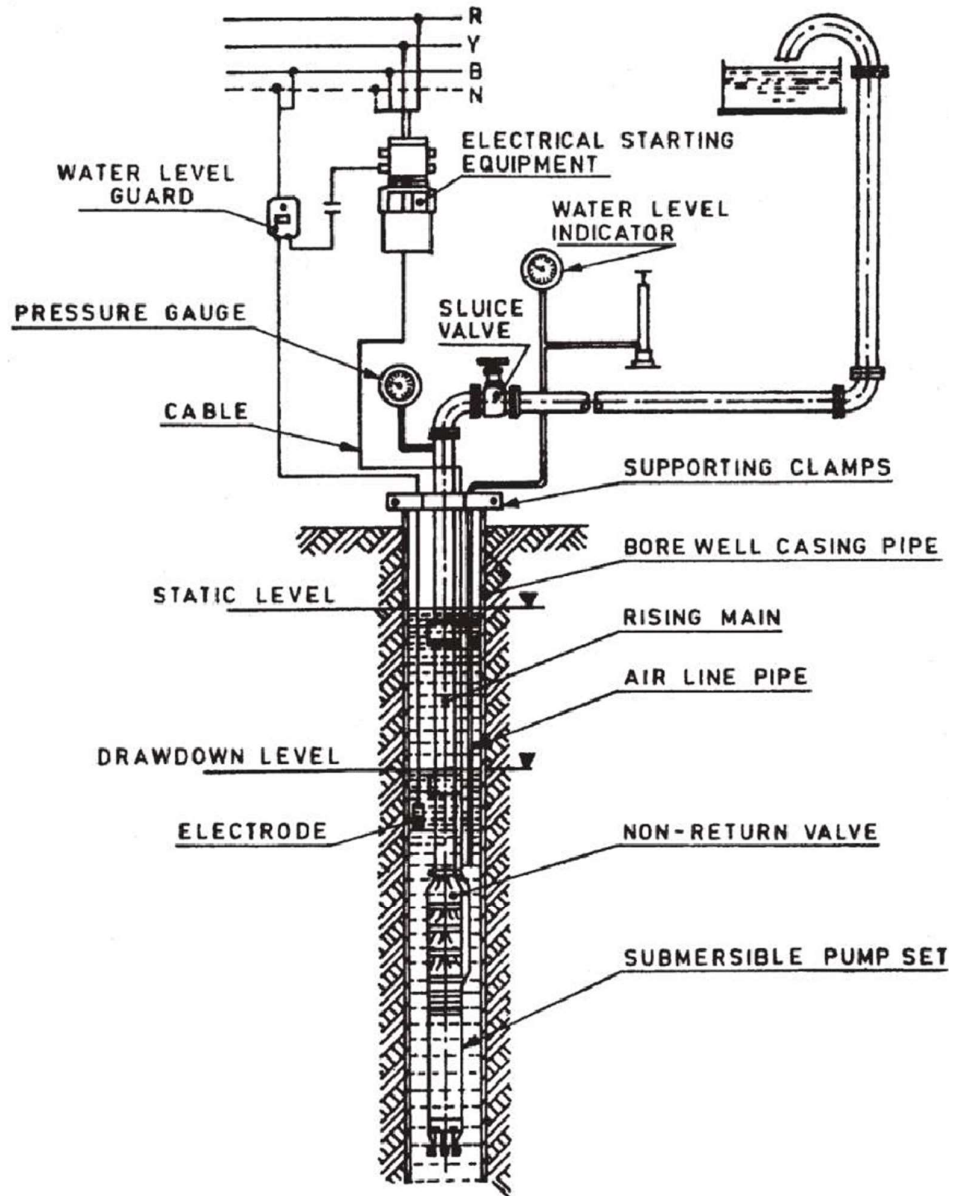


FIG 4 TYPICAL SUBMERSIBLE PUMPSET INSTALLATION

**Table 1 Typical Materials for the Parts of the Submersible Motor**  
**(Clause 5.1)**

SI No.	Name of the Part	Material	Indian Standard and Grade, If Any
(1)	(2)	(3)	(4)
i.	Bearing housing and base	Grey cast iron	IS 210 Gr FG 200
ii.	Motor shaft	Wrought steel Or Chromium steel	IS 1873, C40  IS 1570 (Part 5) Gr 04 Cr 13, or 12 Cr 13, or 20 Cr 13
iii.	Bearing bush	Leaded tin bronze Or Resin bonded carbon metal-clad Or Rubber Or Rubber-lined	IS 318, LTB 3 or LTB 4 or LTB 5
iv.	Rotor: a) Laminations b) Conductor core	Electrical sheet steel Electro grade copper or Die cast aluminum	IS 648 IS 613 IS 4026
v.	Stator: a) Lamination b) Winding wire 1. Conductor 2. Insulation i. For water filled motors ii. For dry or encapsulated or oil filled or resin- filled motor	Electrical sheet steel Electro grade copper  PVC or polywrap copper conductor Super enameled	IS 648 IS 613  IS 8783 Insulation details as covered in IS 13730 (Part 34)
vi.	Breather diaphragm	Nitrile rubber	
vii.	Thrust bearing	Vulcanized fibre versus chromium steel or graphite versus graphite or vulcanized fibre versus bronze	
viii.	Cable gland	Nitrile rubber	
ix.	Cable: a) Conductor b) Insulation	Electro grade copper PVC or with polymer and /or sheathing	IS 694
x.	Stator casing	Grey cast iron or Carbon steel (sheet or pipe) or stainless steel sheet	IS 210, FG 200 IS 1570 (Part 5) Gr 20 Cr 13



**NOTE** — Use of the materials containing hazardous substance like lead beyond permissible portion shall be phased

### **5.3 Recommendation for Selection of Submersible Cable**

5.3.1 The cable shall be insulated and sheathed with suitable polymer. It shall be flexible 3-core or 4-core flat type (or) with insulated leads. The requirements of the flat cable shall be as agreed between the manufacturer and the user. The size of the conductor shall be adequate and suitable for continuous use under water and in air. Refer Table 3 and Table 4 of IS 14536 for cable selection.

5.3.2 The purchaser may specify the actual length of the cable required for the motor. In the absence of this information, the motor shall be supplied with a cable length of minimum 2 m.

5.3.3 In case a joint is required to be made between the lead cable supplied with the motor and the user's cable, a detailed procedure to make a watertight jointing shall be supplied by the motor manufacturer. Refer 6.31.1 of IS 14536.

5.3.4 The size of the conductor and the length of cable should be suitably selected so that the voltage drop between the control panel and the motor terminals does not exceed three percent of the rated voltage.

### **5.4 Earthing**

5.4.1 Motor shall have suitable provision for earthing to facilitate earthing of the motor as per clause 11.1 of IS 15999 (Part 1) at the time of installation.

5.4.2 In case GI pipes are used for the purpose of earthing the motor, earthing connection may be made to the discharge pipe clamps.

5.4.3 All the materials and components for the motors shall be suitable for application in respect of corrosion resistance and mechanical performance continuously under water. The typical materials used in the submersible motors are given in Table 1 for the guidance of the manufacturer and the user.

5.4.4 The rotor of the wet type submersible motor shall be provided with suitable coating to protect it from corrosion under water.

5.4.5 The motor shall be provided with a breathing attachment like bellows, diaphragm, etc. to compensate for the volumetric variation of water inside the motor due to changes in the temperature.

### **5.4 Finish of Bearings**

For motors having journal bearings, the surface of the rotor shaft or that of the sleeves when provided at the bearing portion, shall have a surface roughness not higher than 0.75 microns Ra (*see* IS 3073).

### **5.5 Balancing of Rotor**

The rotor shall be dynamically balanced as per grade given in 6.3 of IS 11723 (Part 1).

## **6 PREFERRED VOLTAGE AND FREQUENCY**

### **6.1 Preferred Voltage**

The preferred rated voltage shall be 415 V for three- phase motors and 240 V for single-phase motors (*see* IS12360).

#### **6.1.1 Preferred Frequency**

The preferred rated frequency shall be the standard frequency of 50 Hz.

### **6.2 Voltage and Frequency Variations**

#### **6.2.1 Category 'A'**

The motors shall be capable of delivering rated output with,

- a) terminal voltage differing from this rated value by not more than  $\pm 6$  percent;
- b) frequency differing from its rated value by not more than  $\pm 3$  percent;
- and c) any combination of (a) and (b).

### 6.2.2 Category 'B'

The motor shall be capable of delivering rated output with;

- a) terminal voltage differing from this rated value by not more than + 6 percent and – 15 percent;
- b) frequency differing from its rated value by not more than  $\pm 3$  percent;
- and c) any combination of (a) and (b).

### 6.3 Preferred Output Ratings

The preferred output ratings, in kW, shall be:

- a) Three-phase motors: 0.75, 1.1, 1.5, 2.2, 3, 3.7, 4.5, 5.5, 7.5, 9.3, 11, 13, 15, 18.5, 22, **26, 30, 37,45, 55, 63, 67 and 75**
- b) Single-phase motors: 0.37, 0.55, 0.75, 1.1, 1.5 and 2.2

#### NOTES

- 1 For three-phase motor output ratings below and above specified the ratings may be permitted.

### 6.4 Speed

The preferred speed shall correspond to 4 or 2-pole motors [1 500 or 3 000 rev/min (synchronous)].

## 7 DIMENSIONS AND TOLERANCES

### 7.1 Dimensions of Motors

Maximum overall diameter of bore hole submersible motors covered in this standard are 98 mm, 146 mm and 194 mm (*see also* Tables 2, 3, 3A,4, 5, 6, 7, 8 and 9). For 196 mm (*see also* Tables 2, 3, 4, 5, 6, 7, 8, 9 and 10).

NOTE — Motor with overall diameter of greater than 194 mm can be manufactured for 200 mm dia. and above, if required by the user.

**Table 2 Values of Performance Characteristics for 2-Pole, 415 Volt, 50 Hz Three-Phase Water Filled Submersible Motors for Bore Size Nominal 100 mm shall Have Maximum OD of Motor 98 mm.**

(Clauses 7.1 and 11.1)

Sl.No	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Minimum Starting Torque (in Terms of Percentage of Full Load Torque)	Efficiency				
					Percent				
					EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(5)	(6)				
i)	1.1	2 740	4.0	125	56.0	58.6	61.1	63.6	66.0
ii)	1.5	2 740	4.8	125	60.0	62.5	64.9	67.3	69.6
iii)	2.2	2 760	6.9	125	63.0	65.4	67.8	70.0	72.2
iv)	3.0	2 760	9.0	125	63.0	65.4	67.8	70.0	72.2
v)	3.7	2 780	10.6	125	64.0	66.4	68.7	70.9	73.0
vi)	4.5	2 780	12.6	125	67.0	69.3	71.5	73.6	75.6
vii)	5.5	2790	15.5	125	68.0	70.2	72.4	74.5	76.4

NOTE –

- 1. The different levels of efficiencies mentioned are minimum values and no tolerance is applicable.

**Table 3 Values of Performance Characteristics for 2-Pole, 415 Volt, 50 Hz Three-Phase Water Filled Submersible Motors for Bore Size Nominal 125 mm shall Have Maximum OD of Motor 120 mm.**

(Clauses 7.1 and 11.1)

Sl.No	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Minimum Starting Torque (in Terms of Percentage of Full Load Torque)	Efficiency				
					Percent				
					EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(5)	(6)				
i)	1.1	2750	3.6	125	56.5	59.1	61.6	64	66.5
ii)	1.5	2750	4.6	125	63	65.4	67.8	70	72.2
iii)	2.2	2770	6.7	125	64	67.3	69.6	71.8	73.9
iv)	3.0	2770	8.8	125	65	67.9	69.9	71.8	74.1
v)	3.7	2790	10.4	125	66	68.3	70.6	72.7	74.7
vi)	4.5	2790	12.3	125	68.5	70.7	72.9	74.9	76.7
vii)	5.5	2800	15.1	125	70.5	72.6	74.7	76.7	78.5
viii)	7.5	2810	19.9	125	72.5	74.0	75.9	77.8	79.5

**Table 3 Values of Performance Characteristics for 2-Pole, 415 Volt, 50 Hz Three-Phase Water Filled Submersible Motors for Bore Size Nominal 150 mm shall Have Maximum OD of Motor 146 mm.**

(Clauses 7.1 and 11.1)

Sl.No	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Minimum Starting Torque (in Terms of Percentage of Full Load Torque)	Efficiency				
					Percent				
					EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(5)	(6)				
i)	1.1	2750	3.3	125	57.0	59.6	62.1	64.5	66.9
ii)	1.5	2750	4.5	125	66.0	68.3	70.6	72.7	74.7
iii)	2.2	2770	6.5	125	67.0	69.3	71.5	73.6	75.6
iv)	3.0	2770	8.5	125	67.0	69.3	71.5	73.6	75.6
v)	3.7	2790	10.0	125	68.0	70.2	72.4	74.5	76.4
vi)	4.5	2790	12.0	125	70.0	72.2	74.2	76.2	78.1
vii)	5.5	2810	14.5	125	73.0	75.0	76.9	78.8	80.5
viii)	7.5	2810	19.5	125	74.0	76.0	77.8	79.6	81.3
ix)	9.3	2830	25.0	125	75.0	76.9	78.7	80.5	82.1
x)	11.0	2830	29.0	125	76.0	77.9	79.6	81.3	82.8
xi)	13.0	2850	34.0	125	77.0	78.8	80.5	82.1	83.6
xii)	15.0	2850	39.0	125	78.0	79.8	81.4	82.9	84.4

NOTE –

1. The different levels of efficiencies mentioned are minimum values and no tolerance is applicable.
2. For motors with output ratings greater than 15kW and upto 37kW the performance values shall be declared by the manufacturer.

**Table 4 Values of Performance Characteristics for 2-Pole, 415 Volt, 50 Hz Three Phase, Oil Filled Submersible Motors for Bore Size Nominal 150 mm Shall Have Maximum OD of Motor 146 mm**  
(Clauses 7.1 and 11.1)

Sl.No	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Minimum Starting Torque (in Terms of Percentage of Full Load Torque)	Efficiency				
					Percent				
					EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(5)	(6)				
xiii)	2.2	2810	5.8	125	71.0	73.1	75.1	77.1	78.9
xiv)	3.0	2810	7.8	125	73.0	75.0	76.9	78.8	80.5
xv)	3.7	2830	9.1	125	74.5	76.4	78.3	80.0	81.7
xvi)	4.5	2830	11.1	125	76.0	77.9	79.6	81.3	82.8
xvii)	5.5	2850	13.8	125	77.0	78.8	80.5	82.1	83.6
xviii)	7.5	2580	18	125	78.5	80.2	81.8	83.4	84.8
xix)	9.3	2870	23.4	125	79.5	81.2	82.7	84.2	85.5
xx)	11.0	2870	27.3	125	80.5	82.1	83.6	85.0	86.3
xxi)	13.0	2870	32	125	81.5	83.0	84.5	85.8	87.0
xxii)	15.0	2880	36.7	125	82.0	83.5	84.9	86.2	87.4

NOTE –

1. The different levels of efficiencies mentioned are minimum values and no tolerance is applicable.
2. For motors with output ratings greater than 15kW and upto 37kW the performance values shall be declared by the manufacturer.

**Table 5 Values of Performance Characteristics for 2-Pole, 415 Volt, 50 Hz Three Phase, Water Filled Submersible Motors for Bore Size Nominal 200 mm shall have Maximum OD of Motor 196 mm**  
(Clauses 7.1 and 11.1)

Sl.No	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Minimum Starting Torque (in Terms of Percentage of Full Load Torque)	Efficiency				
					Percent				
					EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(5)	(6)				
i)	3.0	2 780	8.5	125	69.0	71.2	73.3	75.3	77.2
ii)	3.7	2 790	10.0	125	70.0	72.2	74.2	76.2	78.1
iii)	4.5	2 800	12.0	125	72.0	74.1	76.0	77.9	79.7
iv)	5.5	2 810	14.5	125	75.0	76.9	78.7	80.5	82.1
v)	7.5	2 820	19.5	125	76.0	77.9	79.6	81.3	82.8
vi)	9.3	2 830	25.0	125	77.0	78.8	80.5	82.1	83.6
vii)	11.0	2 840	29.0	125	78.0	79.8	81.4	82.9	84.4
viii)	13.0	2 850	34.0	125	79.0	80.7	82.3	83.8	85.1
ix)	15.0	2 860	39.0	125	80.0	81.6	83.2	84.6	85.9
x)	18.5	2 860	48.0	125	80.0	81.6	83.2	84.6	85.9

xi)	22.0	2 870	57.0	125	80.0	81.6	83.2	84.6	85.9
xii)	26.0	2870	66	125	81.0	82.6	84.0	85.4	86.7
xiii)	30.0	2870	76	125	81.0	82.6	84.0	85.4	86.7
xiv)	37.0	2870	85	125	82.0	83.5	84.9	86.2	87.4
xv)	45.0	2870	100	125	82.0	83.5	84.9	86.2	87.4
xvi)	55.0	2870	120	125	83.0	84.4	85.8	87.0	88.2
xvii)	63.0	2870	135	125	83.0	84.4	85.8	87.0	88.2
xviii)	67.0	2870	144	125	84.0	85.4	86.6	87.8	88.9
xix)	75.0	2870	158	125	84.0	85.4	86.6	87.8	88.9

NOTE –

1. The different levels of efficiencies mentioned are minimum values and no tolerance is applicable.
2. For motors with output ratings greater than 75kW and upto 150kW the performance values shall be declared by the manufacturer.

**Table 6 Values of Performance Characteristics for 2-Pole, 240 Volt, 50 Hz Single Phase, Capacitor Start and Run (CSR), Capacitor Start and Capacitor Run (CSCR), Water Filled Submersible Motors for Bore Size Nominal 100 mm shall have Maximum OD of Motor 98 mm**

(Clauses 7.1 and 11.1)

Sl.No.	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Efficiency				
				Percent				
				EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(6)				
i)	0.37	2 740	5.3	40.0	42.6	45.1	47.8	50.4
ii)	0.55	2 750	6.2	42.0	44.6	47.1	49.8	52.5
iii)	0.75	2 760	7.5	46.0	48.6	51.3	53.9	56.5
iv)	1.1	2 760	10.5	49.0	51.6	54.3	56.9	59.4
v)	1.5	2 770	13.8	52.0	54.6	57.2	59.8	62.5
vi)	2.2	2 770	19.8	56.0	58.6	61.1	63.6	66.0

NOTES

- 1 The different levels of efficiencies mentioned are minimum values and no tolerance is applicable.
- 2 Minimum starting torque: 30 percent of full load torque.

**Table 7 Values of Performance Characteristics for 2-Pole, 240 Volt, 50 Hz Single Phase Capacitor Start and Run (CSR), Capacitor Start and Capacitor Run (CSCR), Oil Filled / or Encapsulated Oil Filled, Submersible Motors for Bore Size Nominal 100 mm shall have Maximum OD of Motor 98 mm**

(Clauses 7.1 and 11.1)

Sl.No.	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Efficiency				
				Percent				
				EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(6)				
i)	0.37	2 780	4.1	43.0	45.6	48.2	50.9	53.5
ii)	0.55	2 780	5	45.0	47.6	50.3	52.9	55.5
iii)	0.75	2 790	6.7	50.0	52.6	55.2	57.8	60.4
iv)	1.1	2 790	9.5	53.0	55.6	58.2	60.7	63.2
v)	1.5	2 800	12.5	56.0	58.6	61.1	63.6	66.0
vi)	2.2	2 800	16	62.0	64.4	66.8	69.1	71.3

NOTES

- 1 The different levels of efficiencies mentioned are minimum values and no tolerance is applicable.  
 2 Minimum starting torque: 30 percent of full load torque.

**Table 8 Values of Performance Characteristics for 2-Pole, 240 Volt, 50 Hz Single Phase Capacitor Start and Run (CSR), Capacitor Start and Capacitor Run (CSCR), Water Filled Submersible Motors for Openwell Submersible Pumpset (Clauses 14.7.1, 14.8.1, 16.3.1 and 16.5.2)**

(Clauses 7.1 and 11.1)

Sl. No.	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Nominal Efficiency				
				Percent				
				EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(6)				
i)	0.37	2740	5.3	40.0	41.2	42.5	43.7	45.0
ii)	0.55	2 750	6.2	42.0	43.3	44.5	45.8	47.1
iii)	0.75	2 760	7.5	46.0	47.3	48.6	49.8	51.1
iv)	1.1	2 760	10.5	49.0	50.3	51.6	52.8	54.1
v)	1.5	2 770	13.8	52.0	53.3	54.6	55.8	57.1
vi)	2.2	2 770	19.8	56.0	57.3	58.5	59.7	61.0

NOTES

- 1 The different levels of efficiencies mentioned are minimum values and no tolerance is applicable.  
 2 Minimum starting torque: 30 percent of full load torque.

**Table 9 Values of Performance Characteristics for 2-Pole, 415 Volt, 50 Hz Three Phase, Water Filled Submersible Motors for Openwell Submersible Pumpset**

(Clauses 7.1 and 11.1)

Sl.No	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Minimum Starting Torque (in Terms of Percentage of Full Load Torque)	Nominal Efficiency				
					Percent				
					EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(5)	(6)				
i)	1.1	2 780	3.25	125	57.0	58.3	59.5	60.7	61.9
ii)	1.5	2 780	4.5	125	66.0	67.1	68.3	69.4	70.4
iii)	2.2	2 780	6.5	125	69.0	70.1	71.2	72.2	73.2
iv)	3.0	2 780	8.5	125	69.0	70.1	71.2	72.2	73.2
v)	3.7	2 790	10.0	125	70.0	71.1	72.1	73.1	74.1
vi)	4.5	2 800	12.0	125	72.0	73.0	74.0	75.0	75.9
vii)	5.5	2 810	14.5	125	75.0	75.9	76.9	77.8	78.6
viii)	7.5	2 820	19.5	125	76.0	76.9	77.8	78.7	79.5
ix)	9.3	2 830	25.0	125	77.0	77.9	78.8	79.6	80.4
x)	11.0	2 840	29.0	125	78.0	78.9	79.7	80.5	81.3
xi)	13.0	2 850	34.0	125	79.0	79.8	80.7	81.4	82.2
xii)	15.0	2 860	39.0	125	80.0	80.8	81.6	82.3	83.1
xiii)	18.5	2 860	48.0	125	80.0	80.8	81.6	82.3	83.1
xiv)	22.0	2 870	57.0	125	80.0	80.8	81.6	82.3	83.1

NOTE –

1. The different levels of efficiencies mentioned are minimum values and no tolerance is applicable.



2. For motors with output ratings greater than 22 kW and upto 150 kW the performance values shall be declared by the manufacturer.

**Table 10 Values of Performance Characteristics for 4-Pole, 415 Volt, 50 Hz Three Phase, Water Filled Submersible Motors for Openwell Submersible Pumpset**

(Clauses 7.1 and 11.1)

Sl.No	Rated Output kW	Minimum Full Load Speed rpm	Maximum Full Load Current A	Minimum Starting Torque (in Terms of Percentage of Full Load Torque)	Nominal Efficiency				
					Percent				
					EL1	EL2	EL3	EL4	EL5
(1)	(2)	(3)	(4)	(5)	(6)				
i)	1.1	1360	3.4	125	51	52.3	53.6	54.8	56.1
ii)	1.5	1370	4.7	125	59.5	60.7	61.9	63.1	64.3
iii)	2.2	1380	6.8	125	62	63.2	64.4	65.6	66.7
iv)	3.0	1390	8.9	125	62	63.2	64.4	65.6	66.7
v)	3.7	1400	10.4	125	63	64.2	65.4	66.5	67.6
vi)	4.5	1400	12.5	125	65	66.2	67.3	68.4	69.5
vii)	5.5	1410	15.1	125	67.5	68.6	69.7	70.8	71.8
viii)	7.5	1420	20.3	125	68.5	69.6	70.7	71.7	72.8
ix)	9.3	1420	26	125	69.5	70.6	71.6	72.7	73.7
x)	11.0	1430	30.2	125	70	71.1	72.1	73.1	74.1
xi)	13.0	1430	35.4	125	71	72.0	73.1	74.1	75.0
xii)	15.0	1430	40.6	125	72	73.0	74.0	75.0	75.9
xiii)	18.5	1430	49.9	125	73	74.0	75.0	75.9	76.8
xiv)	22.0	1430	59.3	125	75	75.9	76.9	77.8	78.6

NOTE –

1. The different levels of efficiencies mentioned are minimum values and no tolerance is applicable.
2. For motors with output ratings greater than 22 kW and upto 300 kW the performance values shall be declared by the manufacturer.

### 7.1.1 Dimension of Shafts of Submersible Motors for Borehole Pumps

Recommended dimensions for shafts of submersible motors for borehole pumps are given in Fig. 5 to 7.

### 7.1.2 Tolerances

For motors with anti-friction bearings, the accuracies of shaft extension runout, concentricity of mounting rabbet and face runout, if not otherwise specified, shall be of normal class given in Table 6 and Table 7 of IS 2223 for all sizes of submersible motors for boreholes 100 mm to 200 mm.

For motors with journal bearings, the face run out on the spigot and shaft run out shall not be more than 125 microns and eccentricity shall not be more than 100 microns. The method of measurement shall be as per Fig. 8 to Fig. 10.

## 8 TYPE OF DUTY

The motor shall be of continuous duty (Type S1) specified in IS 15999 (Part 1).

## 9 LIMITS OF TEMPERATURE RISE

The temperature rise of insulated windings of stator shall meet the requirements given in 19.

## 10 OVERLOADS

The motors shall meet the requirements specified in 18.

## 11 PERFORMANCE CHARACTERISTICS

The motors shall comply with the requirements given in 17.

### 11.1 Efficiency

The statement of efficiency at rated load of the motor shall be made by the manufacturer. The values for 2- pole motors shall not be inferior than those given in Tables 2, 3, 4, 5, 6 and 7. The values of 4-pole motors are under consideration.

#### NOTES

- 1 For determination of efficiency of three-phase submersible motors by summation of losses method as outlined in IS 4029, the stator copper losses  $I^2R$  shall be calculated using the value of resistance as at 50°C for motors wound with PVC / Poly wrap insulation and 75°C for motors wound with enamelled copper wires.
- 2 For determination of efficiency of single-phase submersible motors by method as outlined in IS 7572.

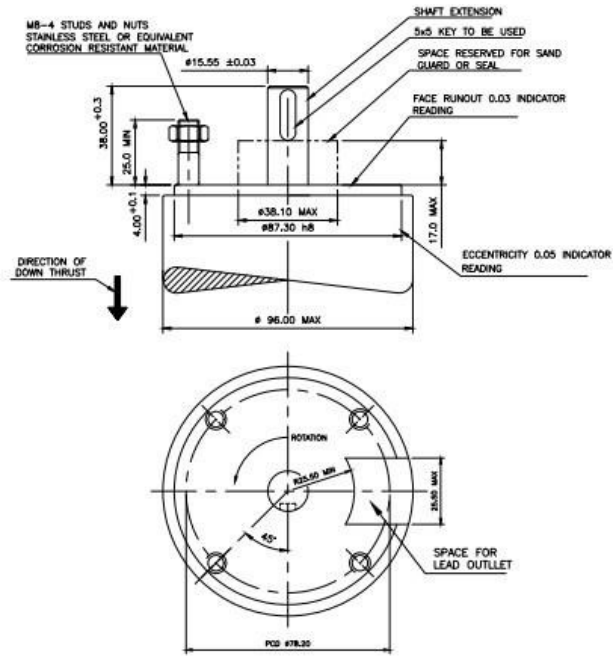
## 12 TERMINAL MARKINGS

The terminal markings or identification of lead wires shall be clearly given for proper connections to the supply system.

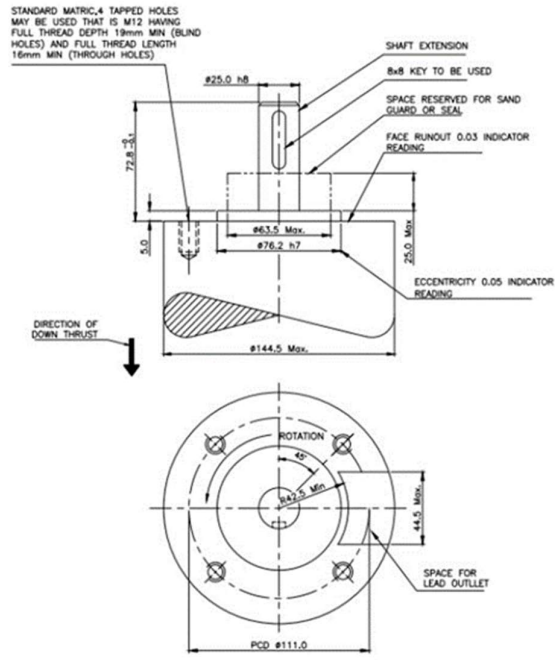
## 13 INFORMATION TO BE GIVEN WITH ENQUIRY AND ORDER

The following general information may also be furnished when enquiring for and ordering the submersible motor.

- a) Level of water above the submersible motor
- b) Length of the electric cable, which is required for the submersible motor. The complete information to be given with enquiry and order is given at Annex B.
- c) Site and operating conditions.
- d) Reference to this standard is IS 9283.
- e) Diameter of the bore.
- f) Level of water above the submersible motor.
- g) Length of cable, which is required for the submersible motor.
- h) Type of duty.
- i) Frequency, in Hz.
- j) Number of phases.
- k) Mechanical output, in kW.
- l) Rated voltage and permitted variation.
- m) Speed, in rev/min, approximate, at the rated output.
- n) If a motor is required to operate between various limits of voltage, current, frequency or speed, the corresponding value of the voltage, current, frequency or speed respectively.
- o) System of earthing, if any, to be adopted.
- p) Particulars of tests required and where they are to be carried out.
- q) Method of starting to be employed.

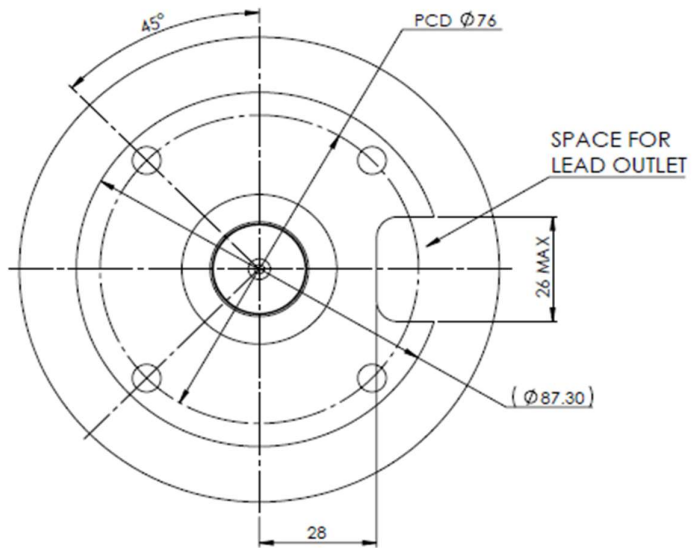
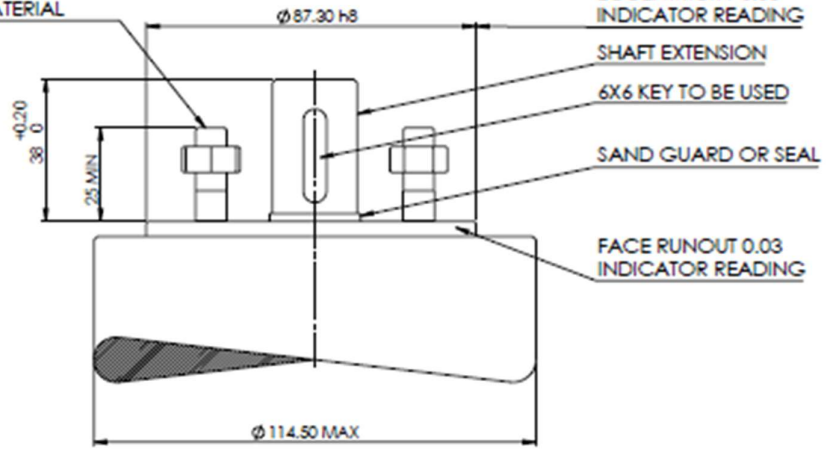


**FIG 5 RECOMMENDED KEY TYPE END CONNECTION OF SUBMERSIBLE MOTOR FOR BORE HOLE PUMPS (100 mm BORE HOLE)**

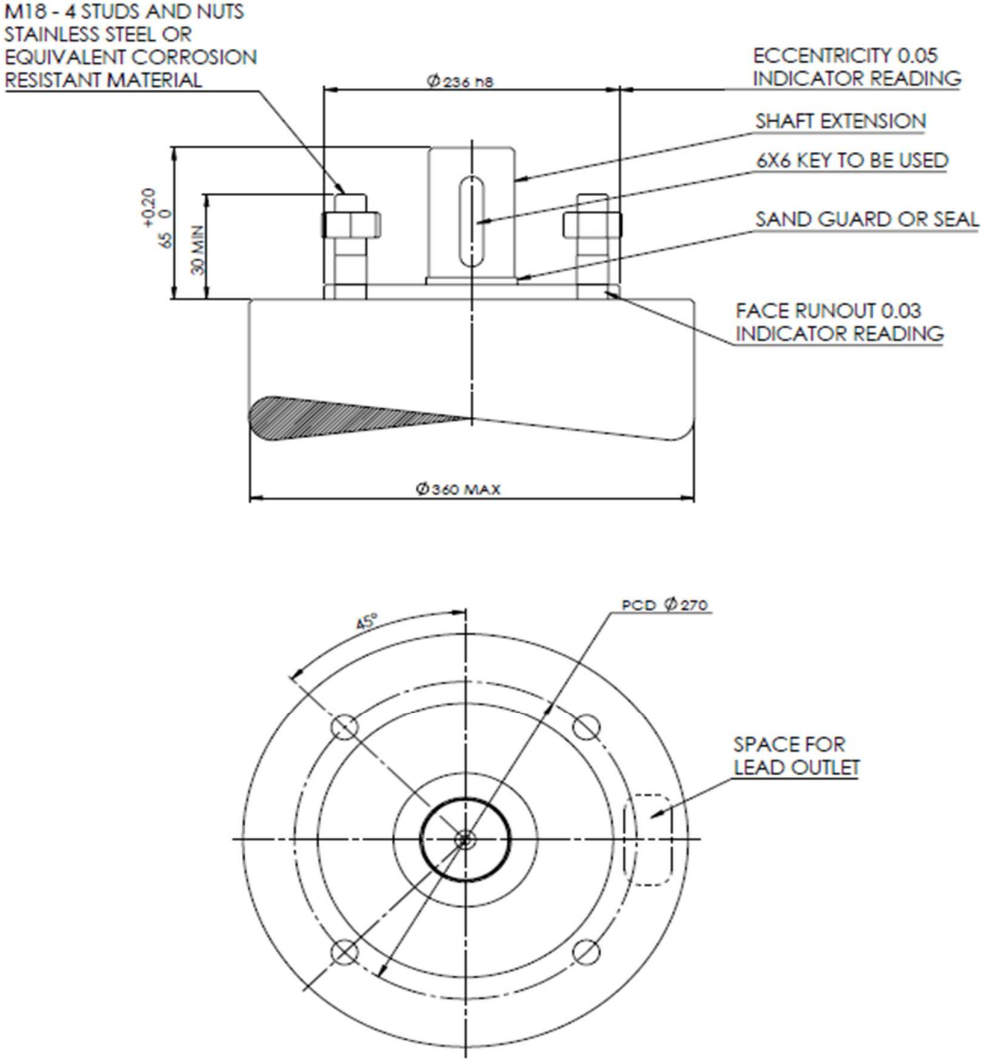




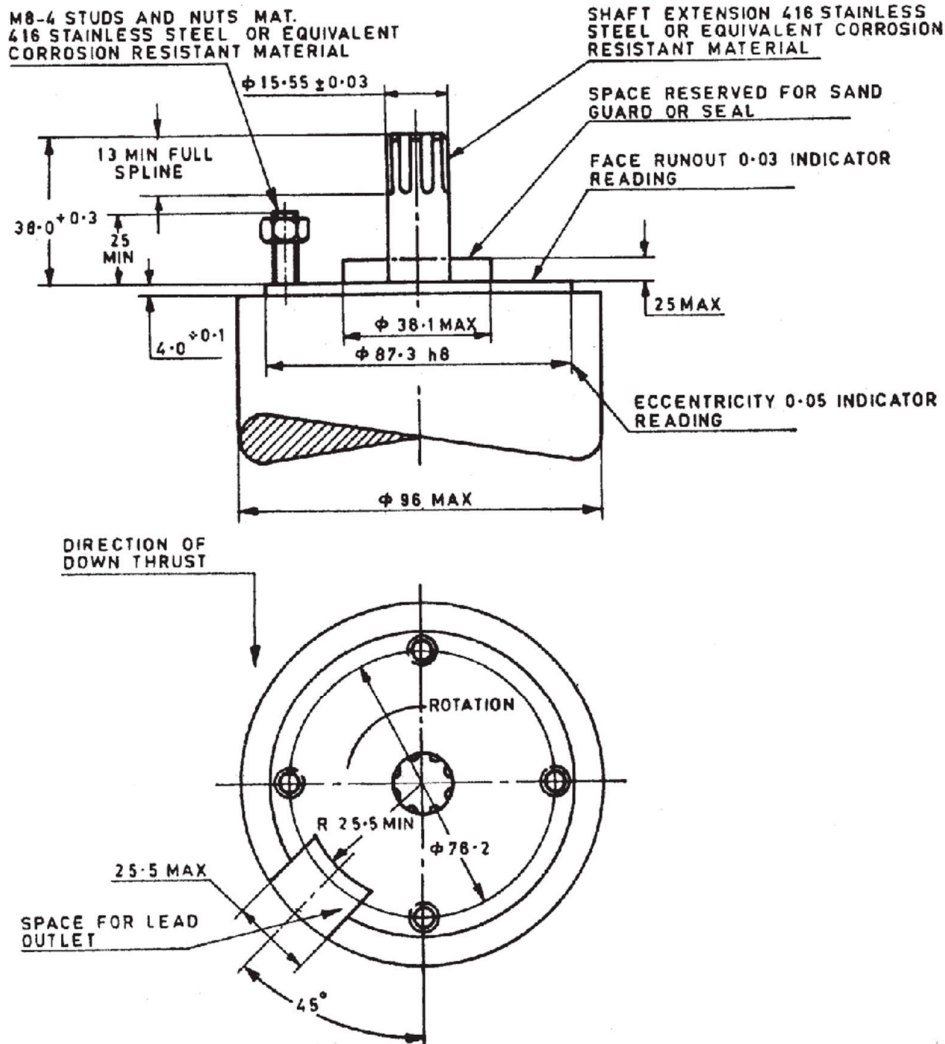
M8 - 4 STUDS AND NUTS  
STAINLESS STEEL OR  
EQUIVALENT CORROSION  
RESISTANT MATERIAL



**FIG 8 RECOMMENDED KEY TYPE END CONNECTION OF SUBMERSIBLE MOTOR FOR BORE HOLE PUMPS (125 mm BORE HOLE)**



**FIG 9 RECOMMENDED KEY TYPE END CONNECTION OF SUBMERSIBLE MOTOR FOR OPENWELL SUBMERSIBLE PUMPS**



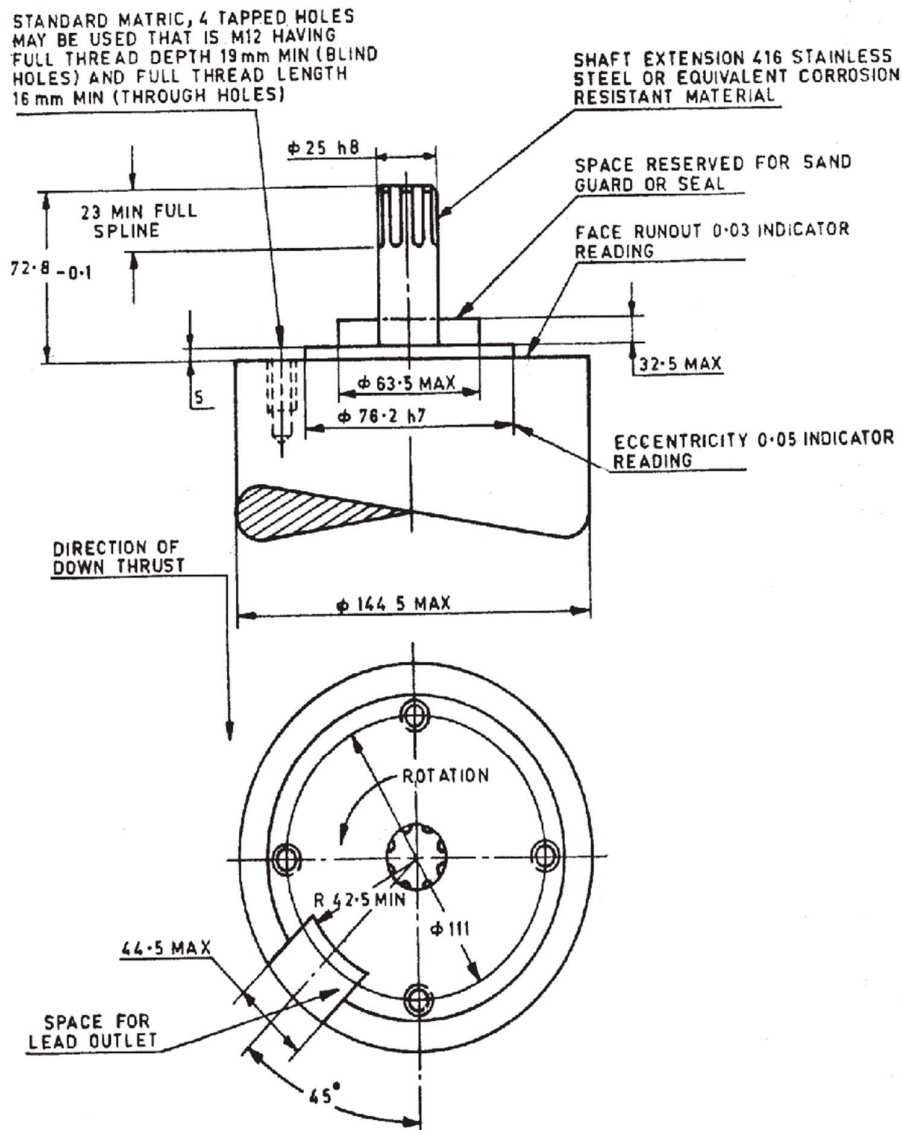
**All dimensions in millimetres.**

**NOTES**

- 1 Normal operating position of motors is vertical with shaft up.
- 2 For spline data (see Fig. 7).
- 3 Substitute measure dia (spline) as  $15.6 - 0.00/-0.05$  for  $15.6 - 0.00/-0.03$ .

**FIG 10 RECOMMENDED END CONNECTION(SPLINE) OF SUBMERSIBLE MOTOR FOR BORE HOLE PUMPS (100 mm BORE HOLE)**



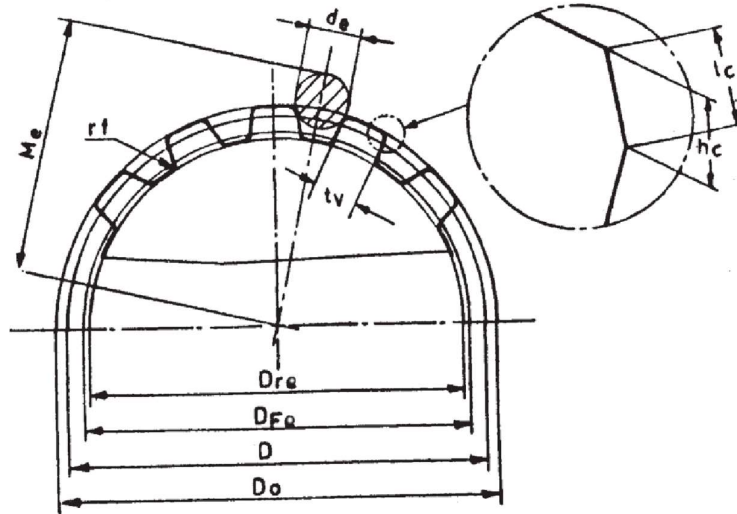


All dimensions in millimetres.

NOTES

- 1 Normal operating position of motors is vertical with shaft up.
- 2 For spline data (see Fig. 7).
- 3 Substitute measure dia (spline) as  $25 - 0.00/-0.05$  for  $25 - 0.00/-0.03$ .

**FIG 11 RECOMMENDED END CONNECTION(SPLINE) OF SUBMERSIBLE MOTOR FOR BORE HOLE PUMPS (150 mm BORE HOLE)**



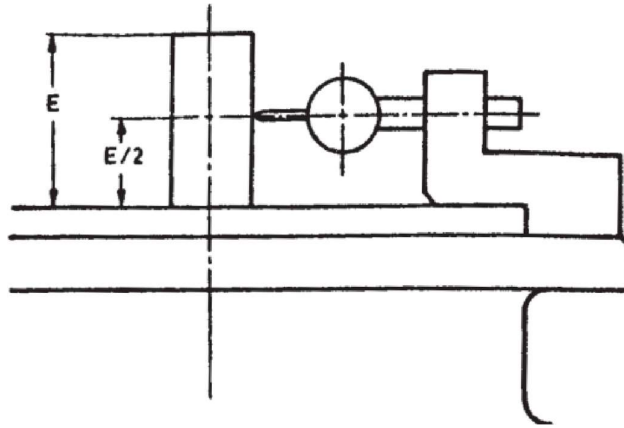
**External Spline Data**  
All dimensions in millimeters.

Description	Motor Suitable for Bore	
	100mm	150mm
No. of teeth, N	14	15
Diametrical pitch, P	24/48	16/32
Pressure angle	30°	30°
Base diameter, Db	12.83	20.62
Pitch diameter, D	14.80 ± 0.1	23.81 ± 0.1
Major diameter, Do	- 0.00	-0.000
	15.60	25.00
Form diameter, DFe	-0.05	-0.05
Minor diameter, Dre	13.70 ± 0.1	22.10 ± 0.1
Effective tooth thickness, tv	13.3 ± 0.1	20.53 ± 0.1
Minimum measurement over pins, Me	1.62 ± 0.03	2.46 ± 0.03
	17.83 ± 0.02	28.25 ± 0.02
Pin diameter, de	2.03	3.05
Chamfer height, he	0.15	0.25
Chamfer height, le	0.2	0.3
Spline length, L Min (Effective)	13	23
Fillet radius, rf	0.1	0.15
Maximum run-out	0.025	0.025
Maximum total indexing	0.033	0.038
Maximum involute flank form error	0.012	0.02
Maximum flank deflection distortion	0.008	0.013
Type of spline	Involute sided	Involute sided
Tolerance class	5	5

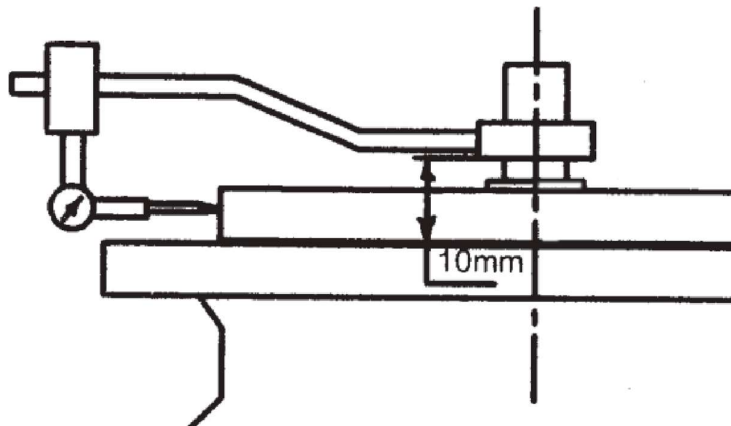
NOTES

- 1 Type of Spline : Involute
- 2 Type of Fit : Fillet Root Side Fit
- 3 Tolerance Class : 5
- 4 All dimensions in millimetres except diametral pitch.

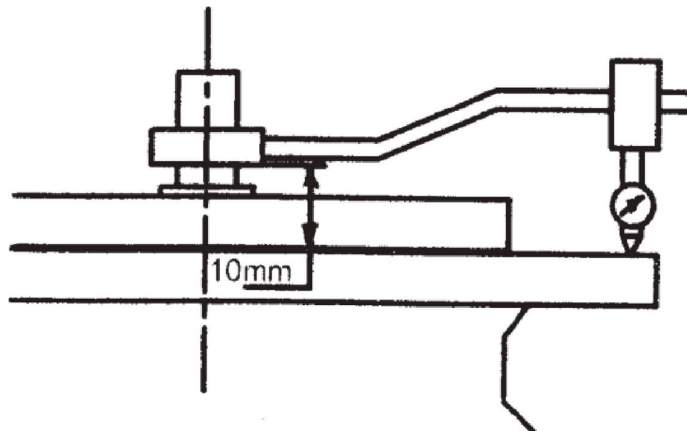
**FIG 12 RECOMMENDED SPLINE FOR SHAFT EXTENSION FOR SUBMERSIBLE MOTOR**



**FIG 13 MEASUREMENT OF SHAFT EXTENSION RUN-OUT**



**FIG 14 MEASUREMENT OF CONCENTRICITY OF MOUNTING SPIGOT AND SHAFT**



**FIG 15 MEASUREMENT OF FACE RUNOUT**

## 14 RATING PLATE

The motor shall have the rating plate giving the following information:

- a) Reference to this Indian Standards, that is IS 9283
- b) Induction motor;
- c) Name of the manufacturer;
- d) Manufacturer's serial number;
- e) Type of duty;
- f) Frequency, in Hz;
- g) Number of phases;
- h) Rated output, in kW;
- j) Rated voltage and winding connections;
- k) Current, approximate, at rated output, in A;
- m) Speed in at rated output, in rev/min;
- n) Efficiency, in percent; and
- p) Category of motor and bore size, in mm.
- q) Type of Motor

In addition, the manufacturer's serial number shall be punched at a convenient place for easy identification.

## 15 BIS Certification Marking

The motor may also be marked with BIS Standard Mark.

**15.1** The use of the Standard Mark is governed by the provision of Bureau of Indian Standards Act, 2016 and the Rules and Regulations made thereunder. The details of conditions under which the license for the use of the Standard Mark may be granted to the manufacturers or the producers may be obtained from the Bureau of Indian Standards.

## 16 CLASSIFICATIONS OF TESTS

### 16.1 Type Tests

The following shall constitute the type tests:

- a) Insulation resistance test (both before and after the high voltage test)
- b) High voltage test
- c) Measurement of stator resistance
- d) No load running of motor and reading of voltage, current, power input and speed
- e) Reduced voltage running up test at no load
- f) Locked rotor readings of voltage, current, power input and torque of motors
- g) Full load reading of voltage, current, power input and slip;

**NOTE** — Pump may be used as a loading device.

- h) Performance characteristics
- j) Temperature rise test at rated voltage
- k) Temperature rise test at reduced voltage
- m) Momentary overload test (as per agreement between the manufacturer and the purchaser)
- n) Leakage current test at rated voltage at no load.

**NOTE** — The recommended proforma for preparing a type test certificate is given in Annex C.

### 16.2 Routine Tests

The following shall constitute the routine test:

- a) Insulation resistance test (before high voltage test only)
- b) High voltage test
- c) No load running of motor and reading of current, voltage, power, and speed
- d) Locked rotor reading of voltage, current and power input
- e) Reduced voltage running up test at no load

**16.3** Tests specified shall normally be made at the manufacturer's premises.

NOTE — For the purpose of this standard, the tests to determine performance characteristics shall be made in accordance with methods specified. IS 4029 and IS 7572

## **16.4 TEST CERTIFICATES**

**16.4.1** Unless otherwise specified when inviting tenders, the purchaser, if so desired by the manufacturer, shall accept manufacturer's certificate as evidence of the compliance of the motor with the requirements of this standard together with a type test (see 16.1) certificate on a motor identical in essential details with the one purchased, together with routine test certificate on each individual motor for a batch of 20 or more similar motors is supplied on one order, type tests, as specified, shall be made on one of these motors, in addition to the other certificates if the purchaser so requires.

**16.4.2** Certificates of routine tests (see 16.2) shall show that the motor purchased has been run and has been found to be electrically and mechanically sound and in working order in all particulars.

**16.4.4** Unless otherwise specified when inviting tenders, the user, if so desired by the manufacturer, shall accept as evidence of compliance of the motors with requirements of this standard, certificates of tests made on a motor identical in essential details with the one purchased and of routine tests on each individual motor.

**16.4.5** Certificate of routine tests shall show that the motor purchased has been run and has been found to be electrically and mechanically sound and in working order in all particulars.

## **17 PERFORMANCE VALUES**

**17.1** Minimum full load speed, maximum full load current, minimum starting torque, efficiency for 2 pole submersible motors of single-phase and three- phase at rated voltage of 240 V and 415 V respectively and suitable for bores of 100 mm, 150 mm and 200 mm shall be in accordance with Tables 2, 3, 4, and 5.

### NOTES

- 1 For three-phase motors, the value of the full load current shall be taken as the average value of the currents measured in the three phases.
- 2 For motor having rated voltage other than 415V for three- phase and 240V for single-phase, values given in Tables 2, 3, 4 and 5 shall be applicable except for the value of maximum full load current, which would be changed, in the inverse proportion of the voltage.
- 3 In case the manufacturer declares superior nominal values of performance than specified in Tables 2, 3, 4, and 5 declared values shall be subject to verification. The observed values of the performance characteristics obtained from the test results shall confirm to the declared values of the manufacturer within the tolerances specified in Table 6.
- 4 Performance values for other motors not specified in this standard (Irrespective of bore sizes, number of poles, and number of phases) shall be declared by the manufacturer.
- 5 Speed is to be corrected for 50 Hz.
- 6 Full Load Test to Determine Efficiency, Power Factor and Slip- The tests shall be carried out at rated voltage and rated frequency.
- 7 For line start / operated permanent magnet motors, efficiency will be determined by direct measurement input-output method for all ratings.

## 17.2 TOLERANCES

Unless otherwise specified, tolerance on performance shall be in accordance with Table 6. Where a tolerance is stated in the other direction, is considered unimportant.

## 18 OVERLOAD TEST

### 18.1 Momentary Excess Torque

The motor shall, whatever their type of construction, be capable of withstanding for 10 s without stalling or abrupt change in speed (under gradual increase of torque) an excess torque of 60 percent of the rated torque the voltage and frequency being maintained at their rated value.

### 18.2 Sustained Overloads

Motors rated in accordance with this standard are not capable of carrying sustained overload.

## 19 TEMPERATURE RISE TEST

**19.1** The temperature rise test of the motor at rated voltage and supply frequency shall be carried out with the motor coupled to a suitable pump for the full load current and the set run continuously for 1 h till steady state temperature is achieved. The set is stopped, and the temperature rise of the stator winding computed by the resistance method shall not exceed 35°C at rated voltage and 45°C at 85 percent of the rated voltage when the set is run for 1 h soon after the test at rated voltage. During the test, the temperature of the cooling water surrounding the motor may not exceed 45°C.

NOTE — Temperature rise test at 85 percent of rated voltage is not applicable for category ‘A’ motor.

### 19.2 Determination of Temperature Rise of Winding by Resistance Method

The temperature rise ( $t_2 - t_1$ ) may be obtained from the ratio of the resistance by the formula:

$$\frac{t_2 + 235}{t_1 + 235} = \frac{R_2}{R_1}$$

Where

$t_2$  = temperature of the winding at the end of the test in °C;

$R_2$  = resistance of the winding at the end of the test measured within 30s after shut down;

$t_1$  = temperature of the winding (cold) at the moment of the initial resistance measurement, in °C; and

$R_1$  = initial resistance of the winding (cold).

For practical purpose the following alternative formula may be found

convenient: Where

$$t_2 - t_1 = \frac{R_2 - R_1}{R_1} (235 + t_1) + (t_1 - t_a)$$

$t_a$  = temperature of cooling medium at the end of the test, in °C

## 20 HIGH VOLTAGE TEST

**20.1** The high voltage test shall be applied between the windings and the frame only to a new and complete motor with all of its parts in place filled with water.

The test shall be carried out at the conclusion of the temperature rise test of the motor where such a test is carried out.

**20.2** The test voltage shall be of the supply frequency and shall be as near as possible to sine wave form. The test shall commence at a voltage of not more than one half of the full test voltage. The voltage shall then be increased to the full value steadily or in steps of not more than 5 percent of the full value, the time allowed for the increase of the voltage from half to full value being not less than 10 s. The full test voltage of 1500 V shall be maintained for 30 s.

**20.3** During the routine testing of motors of rated output up to and including 5.5 kW, the 30 s test may be replaced by test of approximately 5 s at the test voltage given in **20.2**, following the same procedure. Since the test is already made on the windings for acceptance shall, as far as possible, not be repeated. If however, a second test is made at the laboratory or at the special request of the purchaser, the test voltage shall be 80 percent of the voltage (1200 V) given in **20.2**.

**NOTE** — The HV tester shall have adequate capacity to carry the leakage current of the motor.

## 21 INSULATION RESISTANCE TEST

**21.1** The insulation resistance when the high voltage test is applied shall be not less than 5 m $\Omega$ . The insulation resistance shall be measured with a dc voltage of 500 V applied for a sufficient time for the reading of the indicator to become practically steady, such voltage being taken from an independent source or generated in the measuring instrument.

## 22 SPEED

The speed measurement may be conveniently taken by means of a slip coil or any other suitable method.

## 23 LEAKAGE CURRENT TEST

The maximum leakage current value shall not be more than 50 mA at rated voltage at no load. The motor shall be placed on either a rubber mat or a wooden base or any other insulated base. A voltage equal to the rated voltage shall be applied to any supply line and accessible outside metal parts of the motor. The resistance of the test circuit shall be  $2000 \pm 50\Omega$ .

**NOTE** — For safety purposes it shall be ensured during installation that the earthing is capable of taking care of leakage current.

## 24 REDUCED VOLTAGE RUNNING UP TEST AT NO LOAD

Motor shall have the ability to run up to full speed on no load with 60 percent of the rated voltage applied to the motor for three-phase motors and 75 percent of the rated voltage applied to the motor for single-phase motors.

**NOTE** — This test may be made at reduced voltage, when a current at least equivalent to full load current is being taken by the motor.



**ANNEX A**  
**LIST OF REFERRED INDIAN**  
**STANDARDS**

<b><i>IS No.</i></b>	<b><i>Title</i></b>
210 : 2009	Grey iron castings — Specification (fourth revision)
318 : 1981	Specification for leaded tin bronze ingots and castings (second revision)
12615 : 2018	Line operated three phase AC motors (IE Code) "Efficiency Classes and performance specification" (Third Revision)
613 : 2000	Copper rods and bars for electrical purposes —Specification (third revision)
648 : 2006	Cold rolled non-oriented electrical steel sheet and strip — Fully processed type — Specification (fifth revision)
694 : 2010	Polyvinyl chloride insulated unsheathed and sheathed cables/cords with rigid and flexible conductor for rated voltages up to and including 450/750V (Fourth Revision)
1570 (Part 5) : 1985	Schedules for wrought steels: Part5 Stainless and heat resisting steels (second revision)
8034 : 2018	Submersible pumpsets - Specification (Third Revision)
8783 : 1995	PVC insulated winding wires for submersible motors
10804 (Part 2) : 2018	Recommended pumping systems for agricultural purposes: Part 2 submersible pump sets (Third Revision)
11723 (Part1) :1992	Mechanical vibration — Balance quality requirements of rigid rotors: Part 1 Determination of permissible residual unbalance
12360 : 1988	Voltage bands for electrical installations including preferred voltages and frequency
1873 : 2019	Antichill thinner for cellulose nitrate based paints, dopes and lacquers for aircrafts - Specification (First Revision)
1885 (Part 35) : 1993	Electrotechnical vocabulary: Part 35 Rotating machines (first revision)
2223 : 1983	Dimensions of flange mounted ac induction motors (first revision)
3073 : 1967	Assessment of surface roughness
4026 : 1987	Aluminum ingots billets and wire bars (EC grade)
4029 : 2010	Guide for testing three phase induction motors (First Revision)
7538 : 1996	Three-phase squirrel cage induction motors for centrifugal pumps for agricultural applications (first revision)
7572 : 1974	Guide for testing single-phase ac and universal motors

13730 (Part 34): 2000	Specifications for particular types of winding wires: Part 34 polyester enamelled round copper wire, class 130 L (First Revision)
14220 : 2018	Openwell submersible pumpsets -Specification (First Revision)
14582 : 2021	Single-phase small ac electric motors for centrifugal pumps for agricultural applications
15999 (Part 1):2021	Rotating electrical machines - Part 1 : Rating and performance
996: 2009	Single-phase a.c. industrial motors for general purpose

## **ANNEX B**

### **TYPES OF MOTORS**

#### **B-1 TYPES OF MOTORS**

##### **B-1.1 Capacitor Start Capacitor Run (Two-Value Capacitor Motor)**

These motors have higher starting torques and lower starting currents than split-phase motors and are suitable for frequent starting. They have a lower noise level, higher efficiency and power factor than split-phase motors and capacitor start and induction run motors (see B-1.3).

##### **B-1.2 Capacitor Start and Run (Permanent Split Capacitor Motor)**

These motors have lesser starting torque and starting current than capacitor start capacitor run motors and are used where lower starting torques are acceptable. In the running condition, their characteristics are similar to capacitor start capacitor run motors.

##### **B-1.3 Capacitor Start Induction Run (Capacitor Start Motor)**

These motors have higher starting torques and lower starting currents than split-phase motors.

NOTE — This is the least preferred type since the load current is higher and efficiency and power factor are lower than the other two types.

**ANNEX C**

**FORM FOR TEST REPORT OF MOTORS FOR SUBMERSIBLE PUMPSETS**

Name and address of the manufacturer \_\_\_\_\_  
 Purchaser \_\_\_\_\_ Certificate No \_\_\_\_\_  
 Purchase Order No \_\_\_\_\_ Order acceptance No \_\_\_\_\_

**Name Plate Data**

Motor SI No. _____	Voltage _____ V
Output _____ kW	Frequency _____ Hz
Speed _____ rpm	Current _____ A
Data Type _____	Bore Well Size _____ mm

**Test Characteristics**

Loading Condition	Volts	Amps	Watts	Load	Slip Percentage	Power Factor	Efficiency
	V	A	kW				
No Load							
Full Load							

**Temperature Rise Test**

Condition of Test			Watts Input kW	Calculated Output kW	Temperature Rise °C
Hours Run H	Line Voltage V	Line Current A			

At rated Volts  
 At 85 percent  
 of the rated  
 Volts

**Breakaway Torque and Starting Current**

Breakaway torque (Locked rotor) with V _____	Breakaway starting current and power input (Locked	} V _____ W _____
Volts applied _____ kg.m	rotor) with Volts applied	
		A _____ _____ kg.m
Insulation resistance test _____		Megaohm
High voltage test _____		Volt for 30 s
Resistance of winding _____		Ohm
Momentary overload _____		15 s

Test conducted on motor No. \_\_\_\_\_ Approved By \_\_\_\_\_  
 Tested by: \_\_\_\_\_ On: \_\_\_\_\_ Date: \_\_\_\_\_

